



Investigation of Earth Orientation Parameters for VLBA Calibrator Survey sessions

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Content and objectives

- VCS sessions
 - EOP from VCS sessions
 - Error propagation
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- Is it possible to improve source position with fixed a priori EOP?



VLBA Calibrator Survey (VCS)



24 sessions from 1994 – 2007

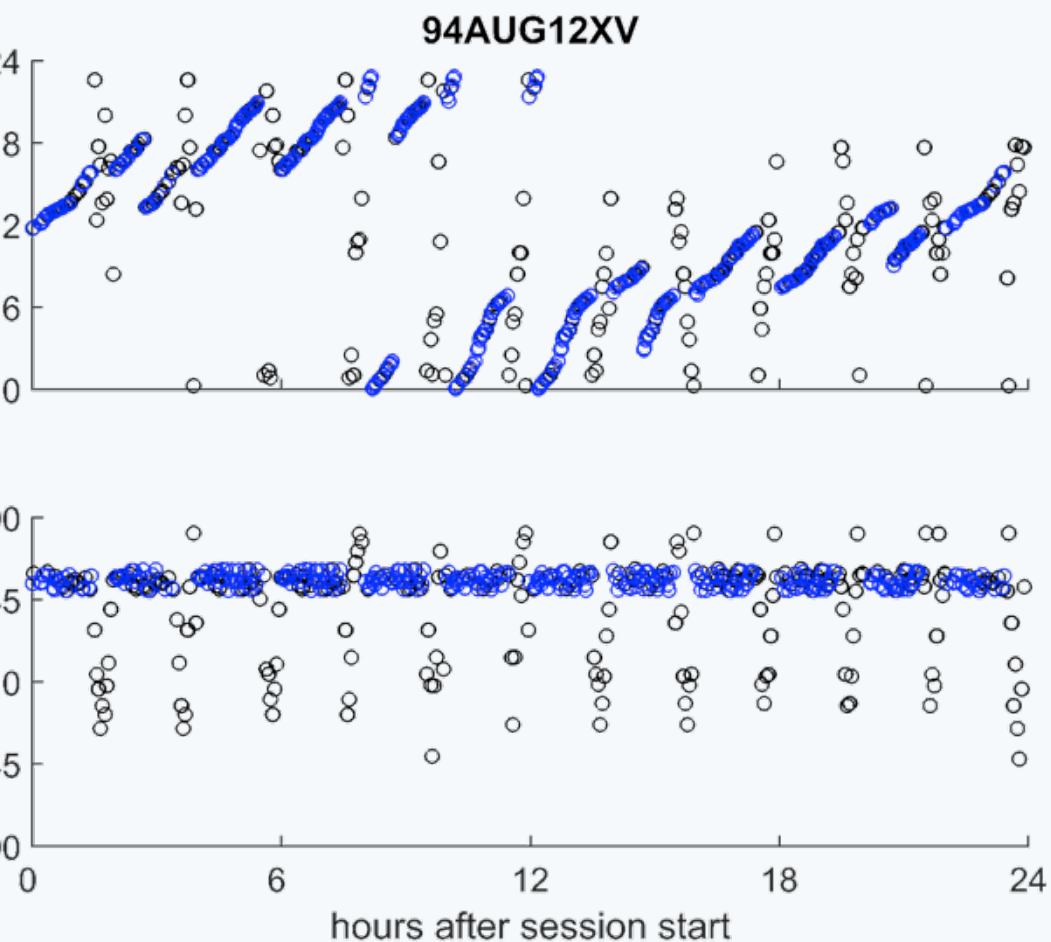
→ Split into 6 campaigns (VCS1 – VCS6)

→ Densify ICRF

→ ICRF2 has 1217 non-VCS sources and 2197 VCS sources



VCS schedules

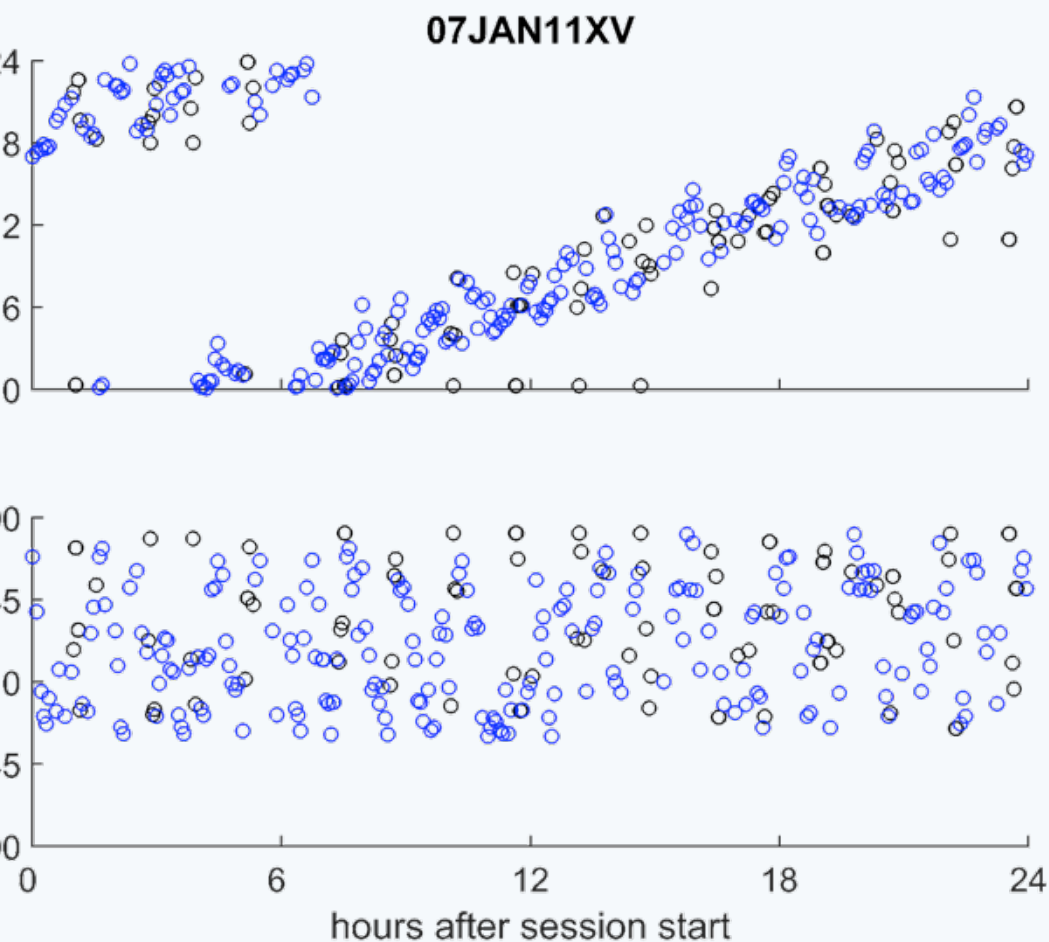


VCS1 \rightarrow piece-wise observations on a meridian + one declination stripes

VCS sources
Non-VCS sources



VCS schedules

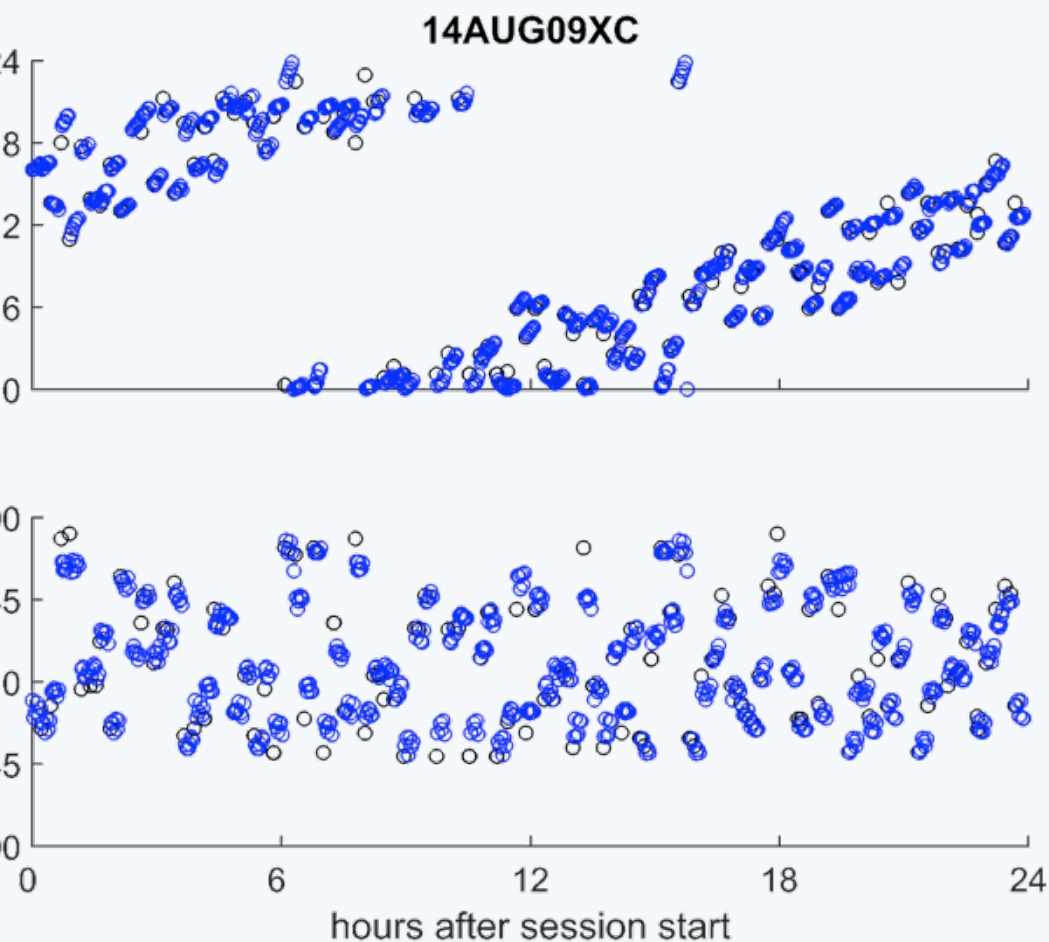


VCS2 – VCS6 → constant meridian + declination spread evenly between -45° and 90°

VCS sources
Non-VCS sources



VCS schedules



VCS-II → constant meridian + declination spread evenly between -45° and 90°

→ Sources are observed in clusters

VCS sources

Non-VCS sources

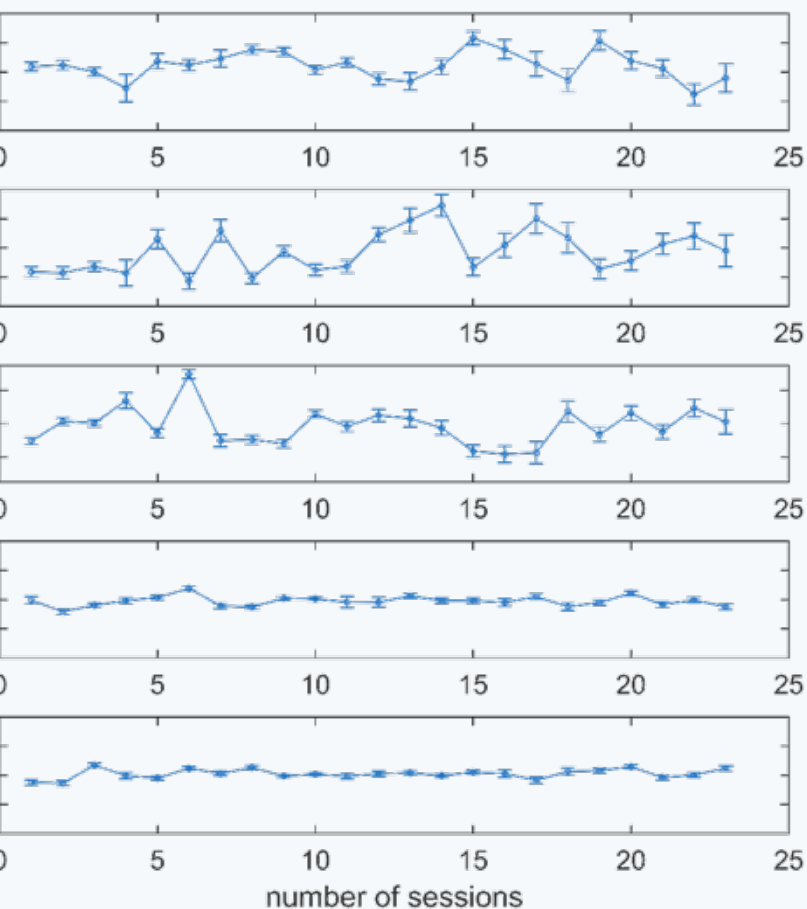
with courtesy of David Gordon



Estimate EOP from VCS sessions

When EOP are estimated from VCS sessions we get large (up to 4 mas) offsets w.r.t. the C04 08 series

→ Network is regional and not suitable for EOP estimation



RMS of the EOP estimates w.r.t. the C04 08 time series

x-pole	0.95 mas
y-pole	1.31 mas
dUT1	0.11 ms
dX	0.34 mas
dY	0.31 mas



Estimate source coordinates from VCS sessions

Solved for:

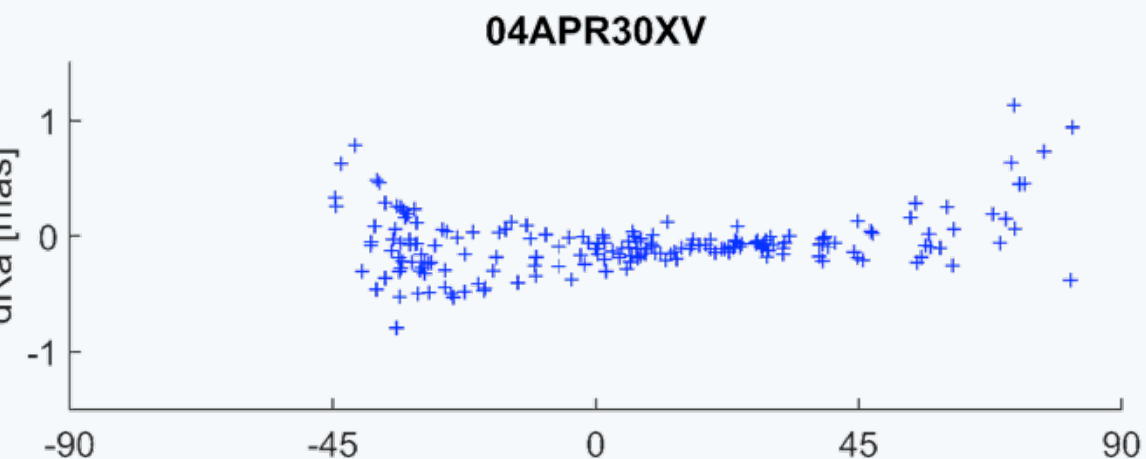
- Station coordinates (NNR + NNT w.r.t. VTRF2008)
- Source coordinates (NNR w.r.t. ICRF2 non-VCS sources)
- Troposphere (ZWD + gradients)
- Clock parameters
- EOP

Difference between two solutions was computed

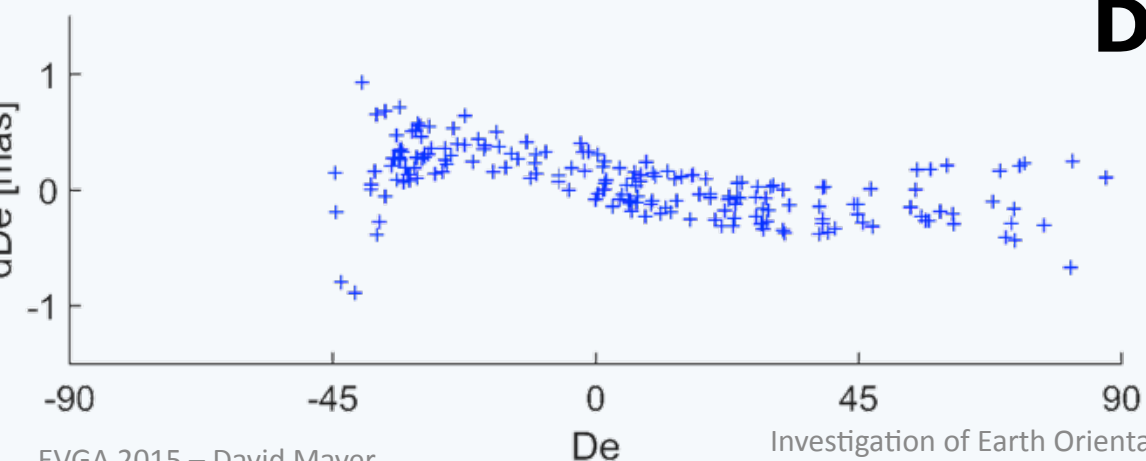
- EOP and source coordinates are estimated simultaneously
- EOP were fixed to the C04 08 time series



Estimate source coordinates from VCS sessions



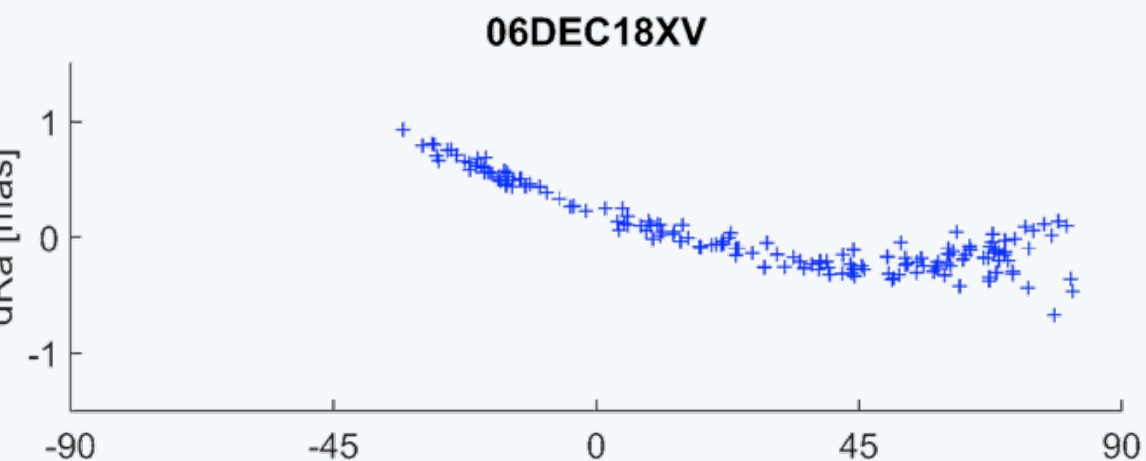
x-pole [mas]	y-pole [mas]	dUT1 [ms]
-0.64	1.90	0.032



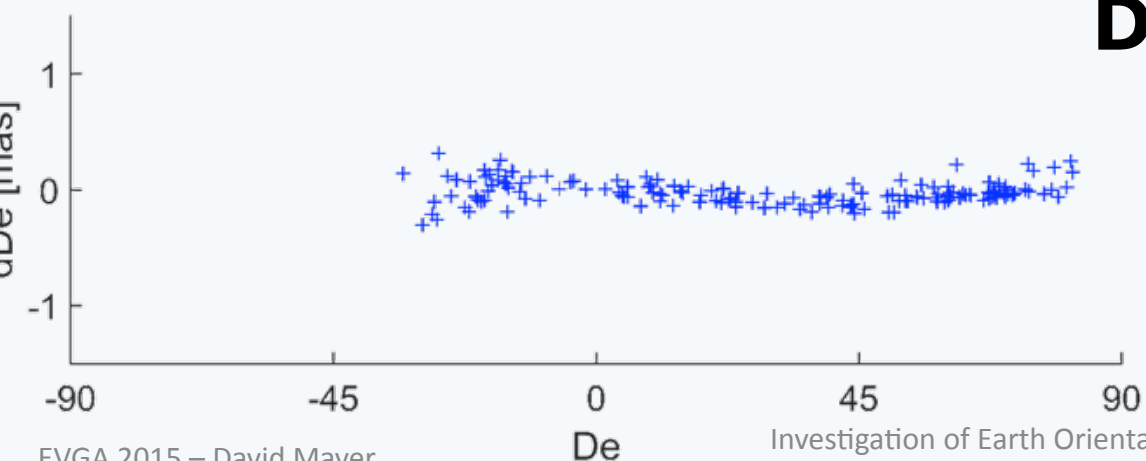
Differences of up to 1 mas



Estimate source coordinates from VCS sessions



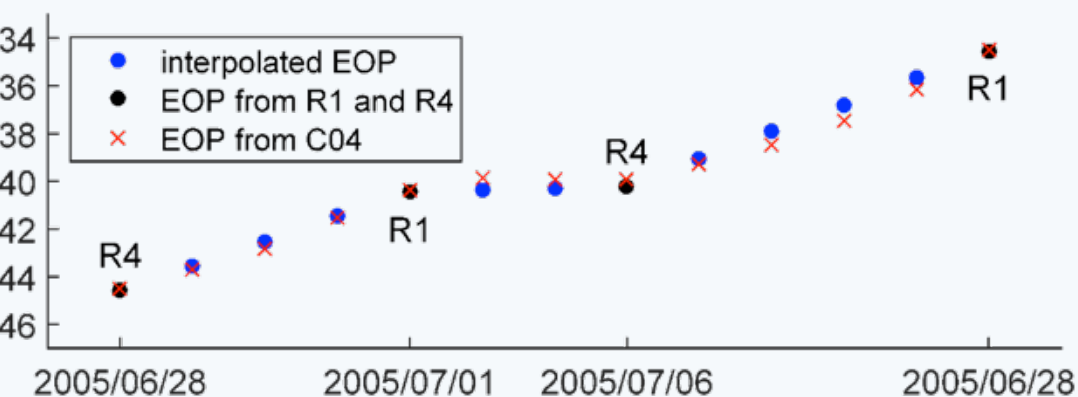
x-pole [mas]	y-pole [mas]	dUT1 [ms]
-1.53	0.81	0.094



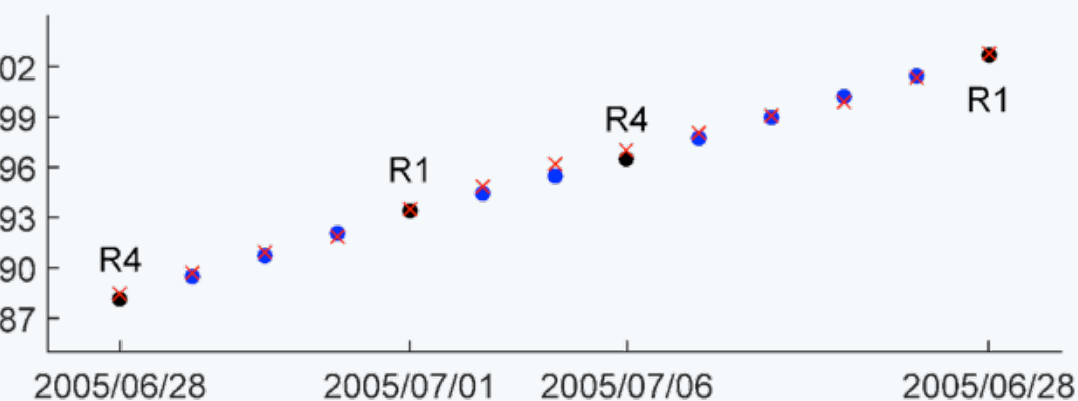
Differences of up to 1 mas



Interpolated a priori EOP



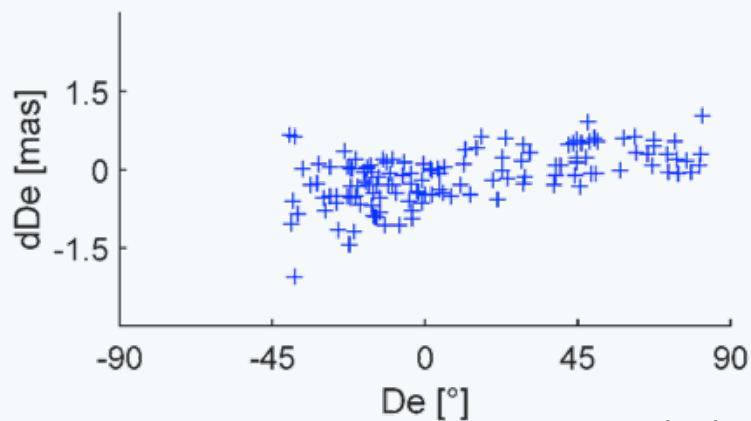
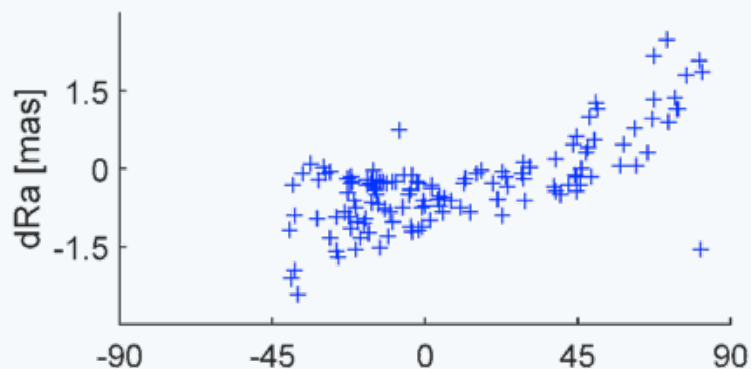
→ Interpolate EOP from R1 and R4 sessions and use them as a priori EOP for VCS sessions



Interpolated a priori EOP

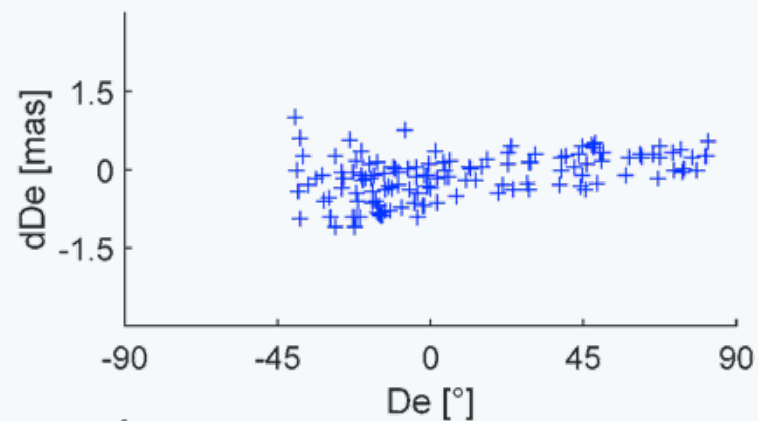
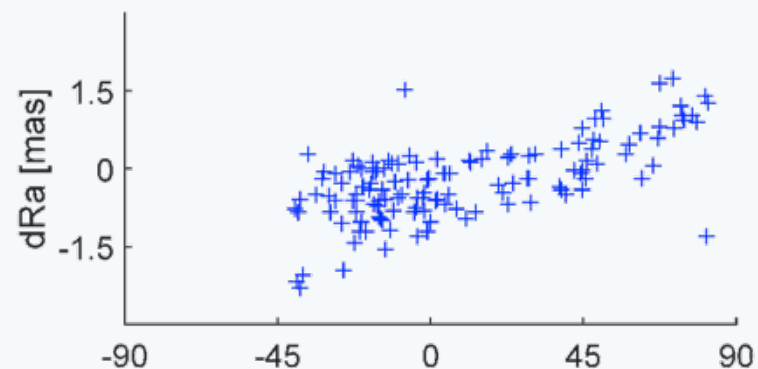
05JUN30XV

C04 EOP
estimated vs. fixed

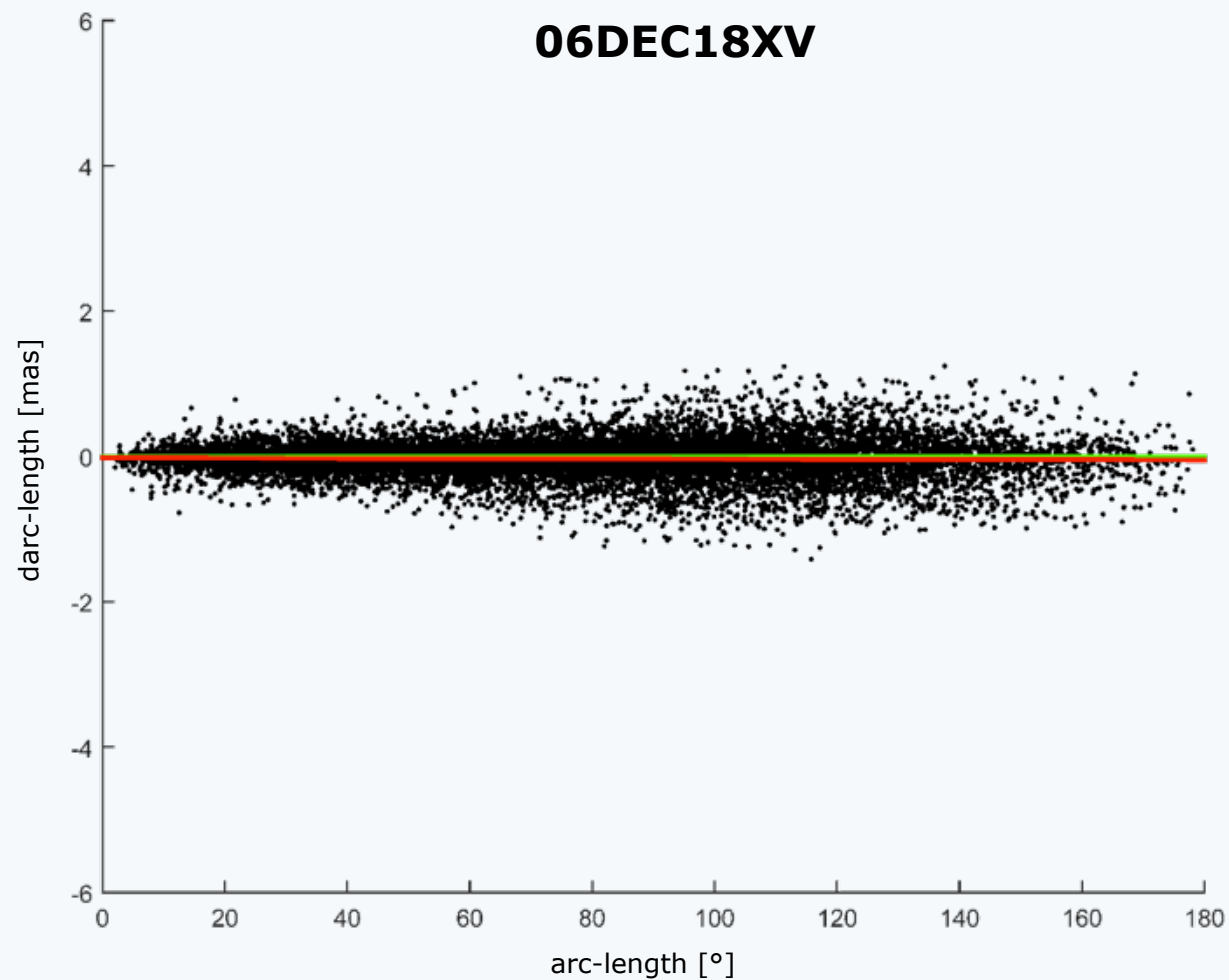


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Interpolated EOP (R1 and R4)
estimated vs. fixed

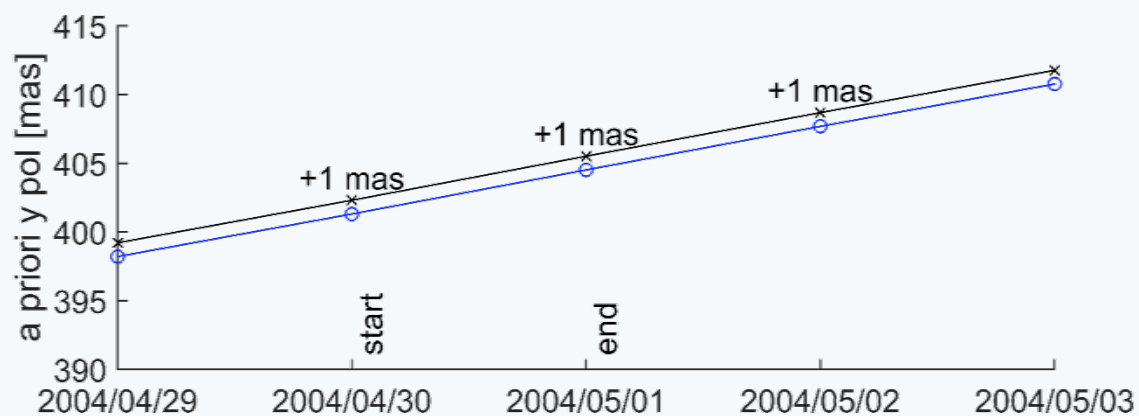
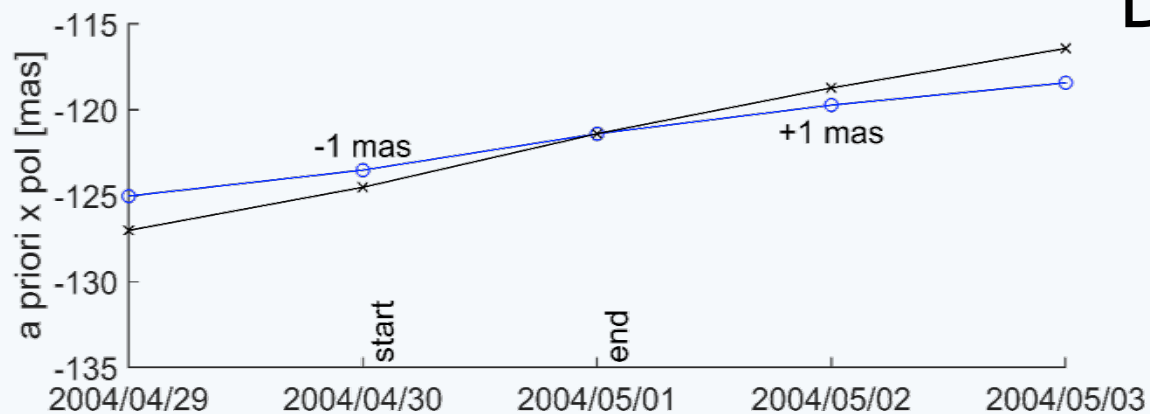


Influence on arc-length



No influence on arc-length visible

Simulations of error propagation

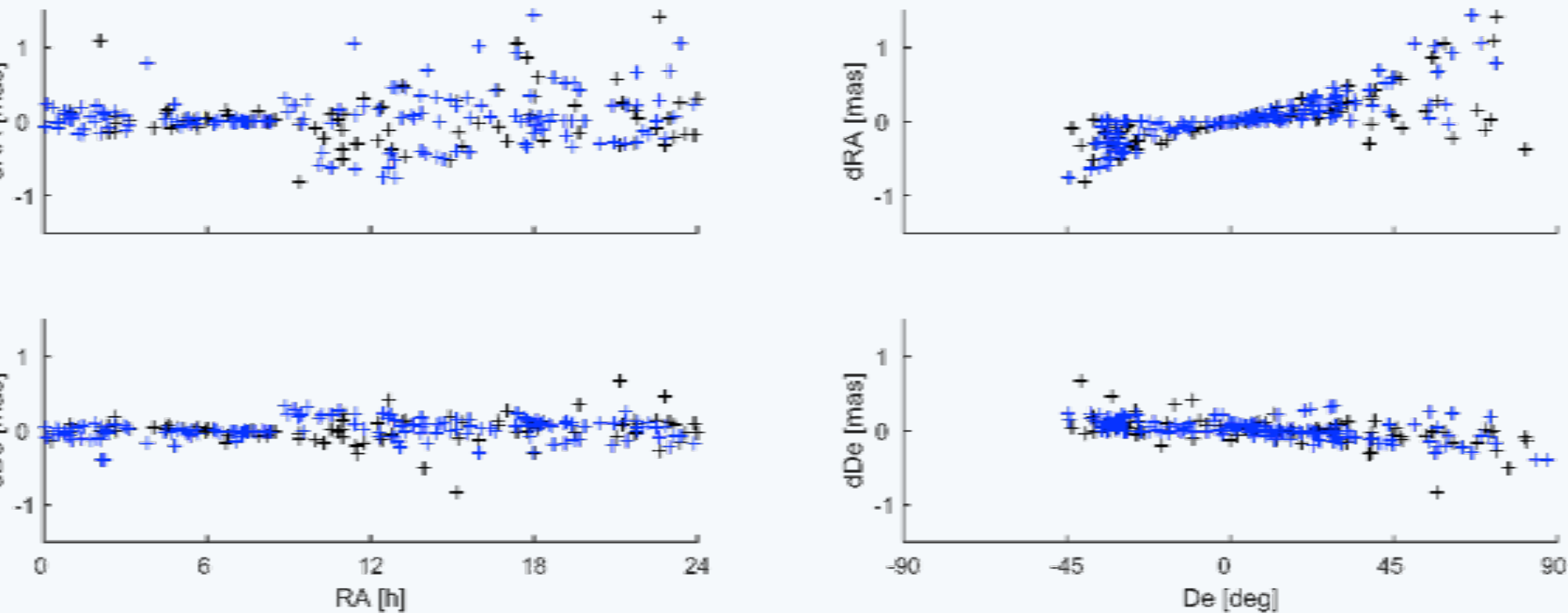


Different errors were investigated

- Error in x- and y-pole rate of 1 mas/day
- Error in dUT1 rate of 1/15 ms/day
- Error in x- and y-pole offset of 1 mas

04APR30XV was used

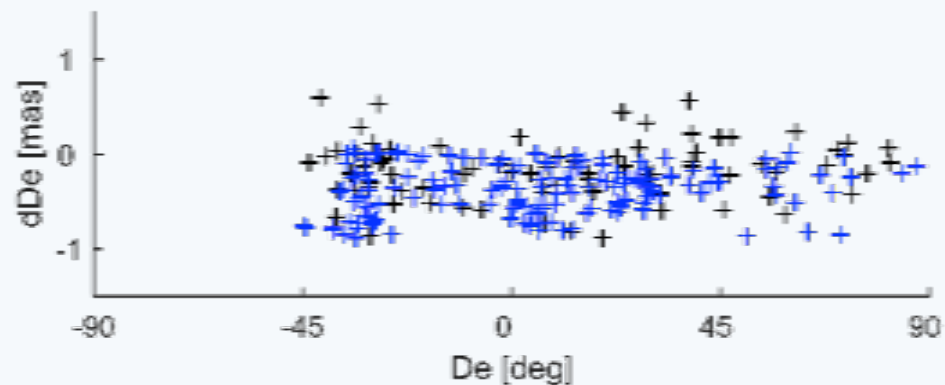
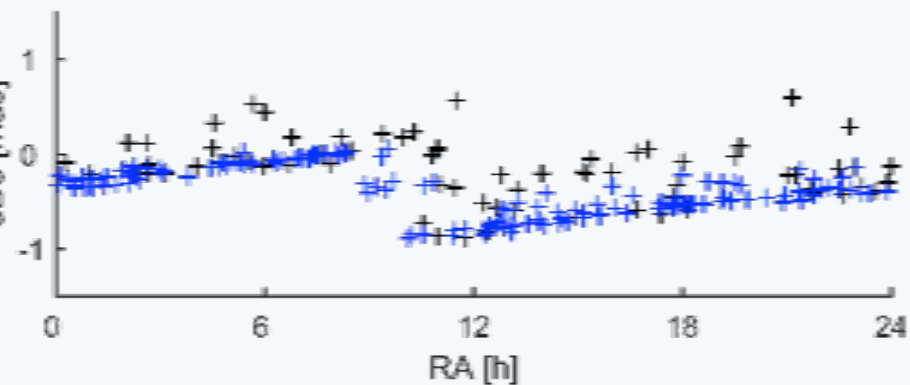
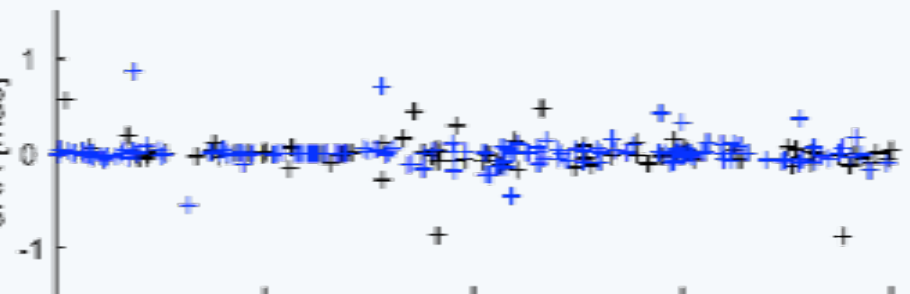
Simulation of error (1 mas/day) in x-pole rate



Only source coordinates estimated

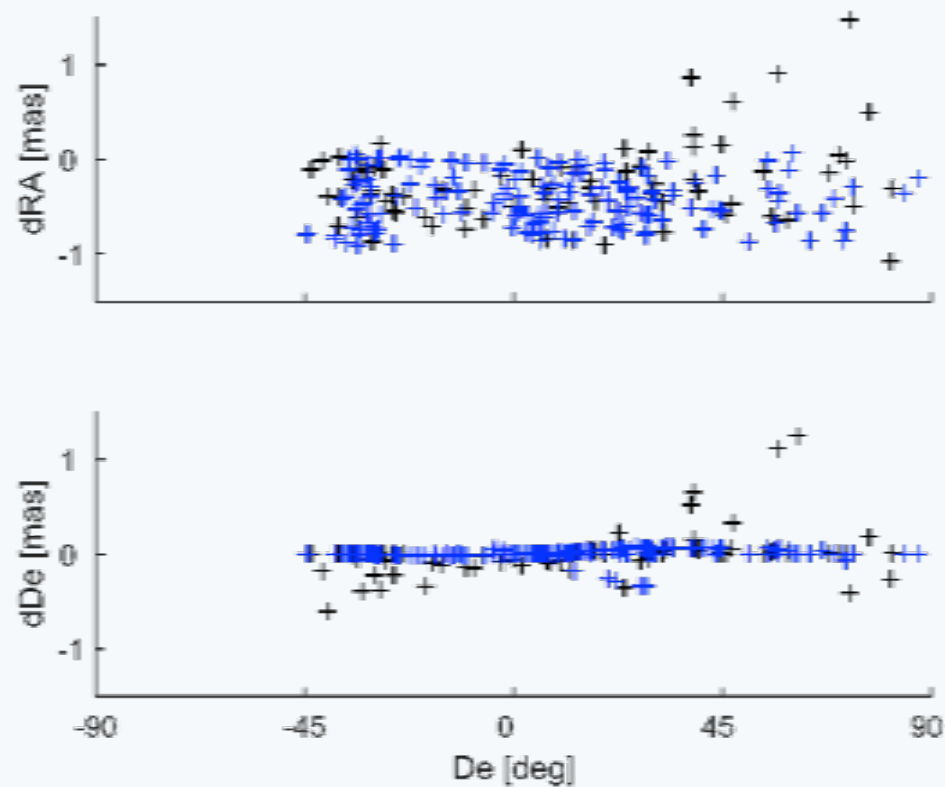
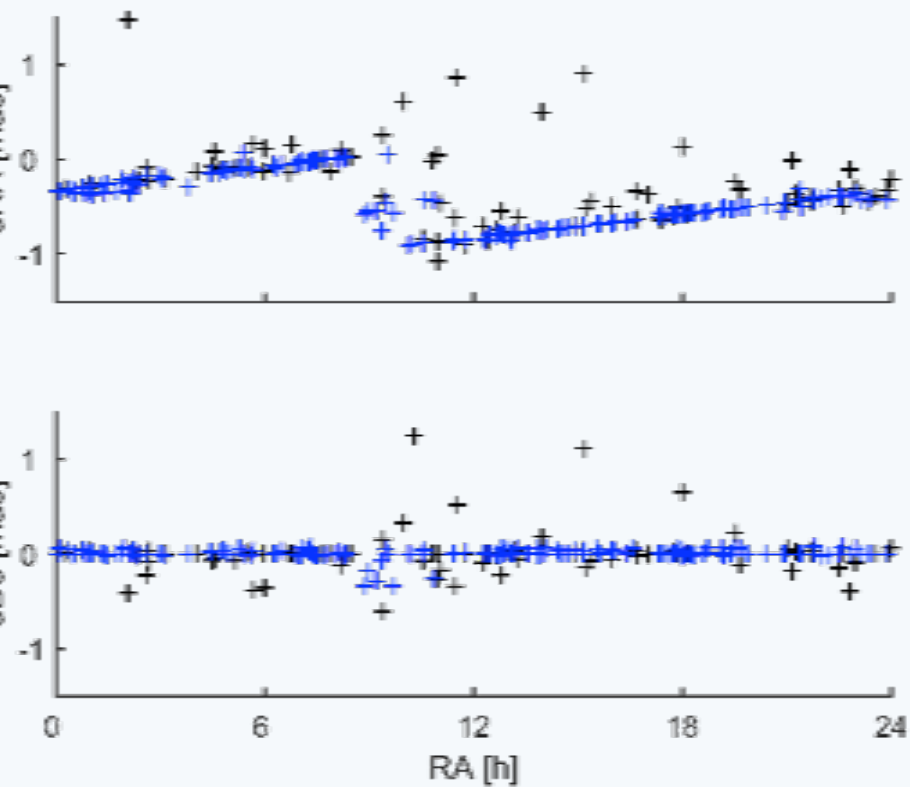


Simulation of error (1 mas/day) in y-pole rate



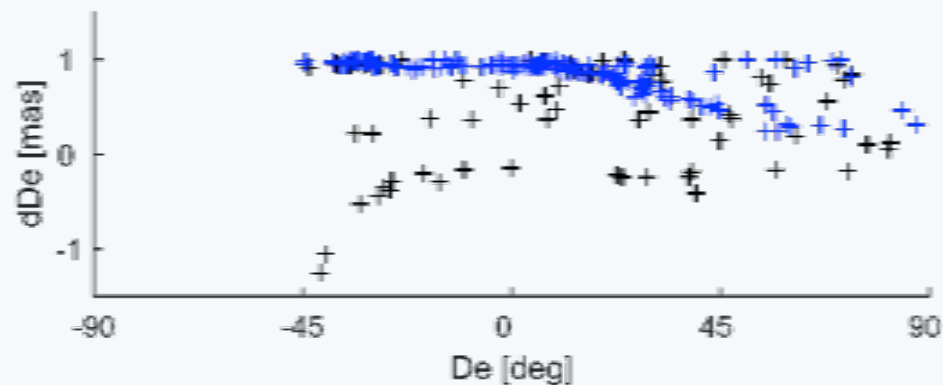
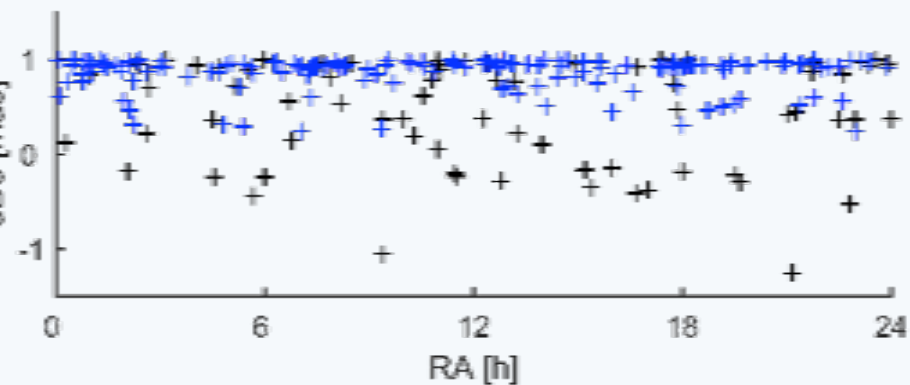
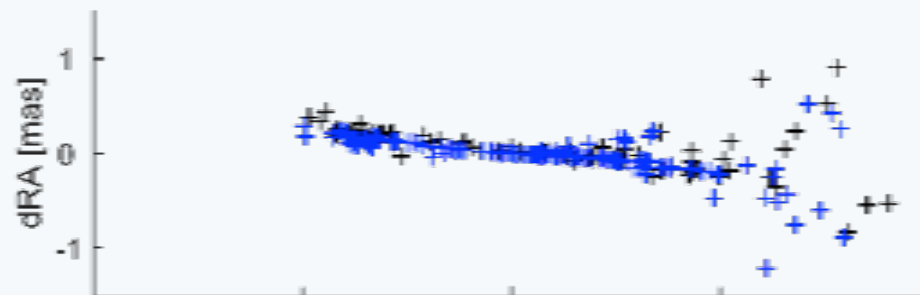
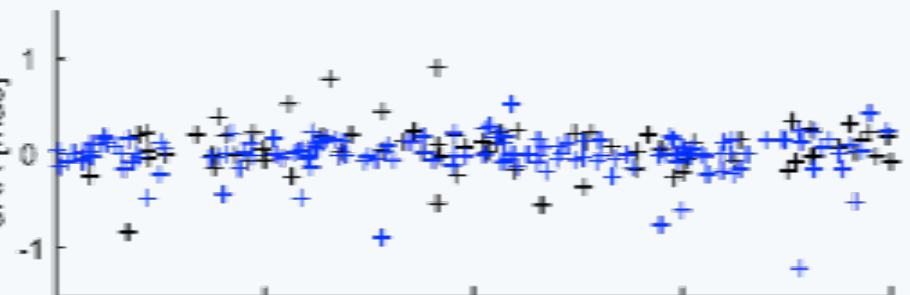


Simulation of error (1/15 ms/day) in dUT1 rate





Simulation of error (1 mas) in y-pole offset





Conclusion

- The regionality of the VCS network results in imperfect EOP estimation
- The difference between source coordinates estimated from a solution where the EOP are fixed and a solution where EOP are estimated is up to 1 mas
- No effect on arc-length
- Errors in rate of y-pole propagate into declination estimates
- Errors in rate of x-pole propagate into right ascension estimates
- Errors in rate of dUT1 propagate into right ascension estimates